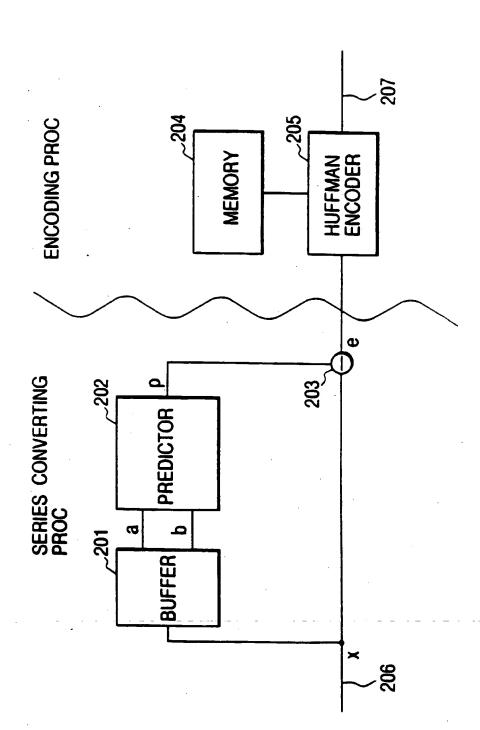


The first term that the fi





APPROVED	O.G. FI	G.
BY	CLASS	SUBCLASS
DRAFTSMAN	<u></u>	ــــــــــــــــــــــــــــــــــــــ

FIG. 3

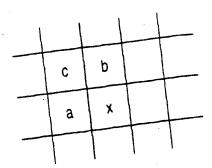


FIG. 4

		CODE
SY	MBOL	1110
	55 54	1111 1100
	3	11100
	2	1.00
	0	0 0
	-1 -2 -3	101
S	-3	
	-254 -255	1111 1111

APPROVED O.G. FIG.

BY CLASS SUBCLASS

DRAFTSMAN

FIG. 5

•		
	PREDICTION ERROR e	COUNT VALUE F(e) (TIMES)
		0
is i	255	0
The state of the s	254	
	•	
	•	
The form that the form the form the form the form the form that the form the fo	2	31
	6	0
	5	98
	. 4	0
	3 2	325
	4	0
	0	1080
,	-1	0
	-2	298
	·3	0
	-4	102
		0
	-6	30
	· ·	•
		•
•		
	-254	0
	-255	0
		- /

APPROVED O.G. FIG.
BY CLASS SUBCLASS
DRAFTSMAN

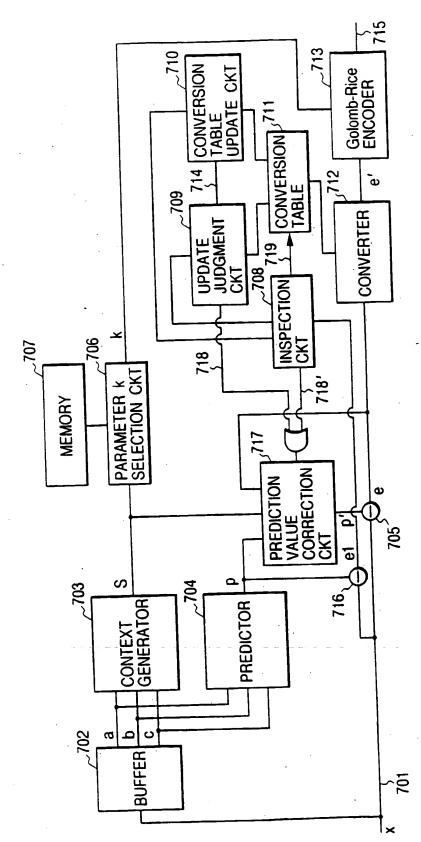
Cont one of the property of the live of th

FIG. 6

\) :

\	
INPUT VALUE (PREDICTION ERROR e)	INTERMEDIATE OUTPUT VALUE M(e)
255	255
254	254
•	
• • • • •	•
6	3
5	Np+2
4	2
3	Np+1
2	1
1	Np
0	0
-1	-Nm-1
-2	-1
-3	-Nm-2
-4	-2
· · · · · · · · · · · · · · · · · · ·	
-5 -6	-3
-0	
•	w.
v. •	
•	-254
-254	-255
-255	-200

FIG. 7



The state of the s

APPROVED O.G. FIG.

BY CLASS SUBCLASS

DRAFTSMAN

pere grue, gert, array, gert, gert,

FIG. 8

CONTEXT S	Golomb-Rice PARAMETER k
0	0
1	1
2	4
3	1
4	3
5	5
. 6	2
7	5
8	6

FIG. 9

	DIFFERENTIAL VALUE (a-c), (b-c)	q(a-c), $q(b-c)$
	4 · · · ·	2
	3	1
-		
	1	1 .
	0	0
	-1	1
	-2	1
	-3	1
	-4 · · · ·	2

APPROVED	O.G. FIG.	
BY	CLASS	SUBCLASS
DRAFTSMAN		

The state of the s

FIG. 10

	SYMBOL (INTERMEDIATE) OUTPUT VALUE) e'	k = 0	k = 1	k = 2
	0	1	0 1	001
	1	0 1	1 1	011
<i>:</i>	2	001	0 0 1	101
	3	0001	101	1 1 1 1
	4	00001	0001	0001
	5	000001	1001	0101

-APPROVED	O.G. FIG.	
BY	CLASS	SUBCLASS
DRAFTSMAN		

FIG. 11A

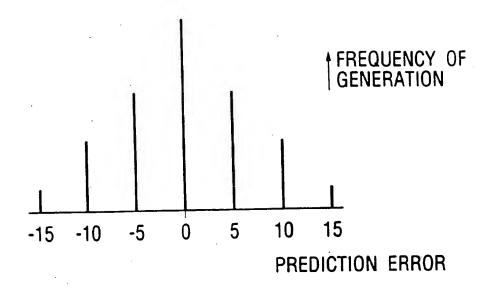
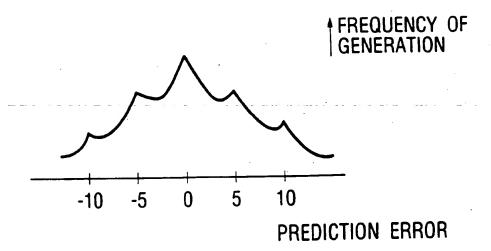


FIG. 11B



CIC 10

The first control of the state of the state

